# CS 6212 DESIGN AND ANALYSIS OF ALGORITHMS

# LECTURE: THE GREEDY METHOD – PART I

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CS 6212 Design and Analysis of Algorithms

The Greedy method

### **OBJECTIVES OF THIS LECTURE**

By the end of this lecture, you will be able to:

- Describe another powerful algorithmic design technique, namely, the Greedy Method
- Explain what optimization problems and optimization techniques are
- Create and explore different greedy policies
- Develop greedy algorithms for several important optimization problems
- Prove non-optimality of some greedy solutions
- Select the right data structures for some greedy algorithms

# OUTLINE

- Introduction to the greedy method
- Applying the greedy method to sorting
- Applying the greedy method to several basic problems
  - Optimal merge patterns
  - The knapsack problem
- A greedy algorithm for the Minimum Spanning Tree (MST) problem
- A greedy algorithm for the Single-Source Shortest Paths problem

#### THE GREEDY METHOD -- BACKGROUND (1) --

- The greedy method is primarily an *optimization* technique
- An optimization problem is either a minimization problem or a maximization problem
- In a minimization problem, there are <u>many</u> solutions, each having a <u>cost</u> associated with it
- Solving a minimization problem means finding the solution that has minimum cost; such a solution is called a *minimum solution*
- In a maximization problem, there are <u>many</u> solutions, each having a <u>profit</u> associated with it, and the goal is to find a *maximum solution*, i.e., the solution with maximum profit

## THE GREEDY METHOD

-- GENERAL STRATEGY --

- For greedy to apply, the solution must consist of a set/sequence of elements
  - The greedy method finds the solution one element after another: the i<sup>th</sup> element in the i<sup>th</sup> step.
- General strategy of the greedy method:
  - At every step,
    - select the **<u>best</u>** element **<u>from</u>** the **<u>remaining input</u>**,
    - delete it from the input, and put it in the output.
- What is "best"?
  - The answer is given by the algorithm designer, and
  - varies from problem to problem, and algorithm to algorithm

The statement "select the best at every step", along with the definition of "best", are referred to as the greedy policy.

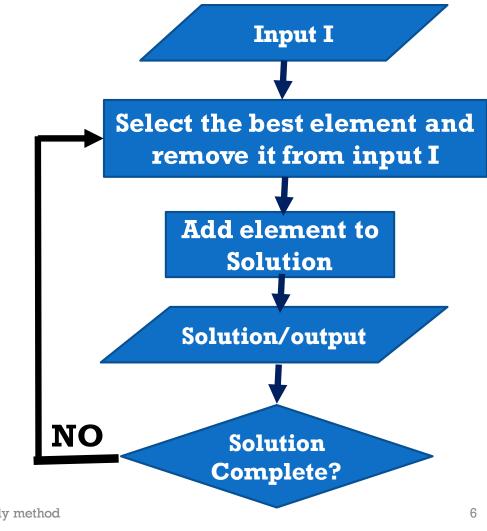
# THE GREEDY METHOD

#### -- TEMPLATE --

**Template** Greedy (input I)

#### begin

Optional: Process I for faster exec while (solution is not complete) do Select the best element x in the remaining input I; Remove x from the input I; Put x next in the output; endwhile end



#### FIRST APPLICATION -- GREEDY SORT --

- Greedy sorting
  - The selection policy: select the minimum of the remaining input
  - That is, best=minimum
  - So the method becomes:
    - While there is input, find the minimum of the remaining input, remove it from the input, and put it next in the output.
- Notes:
  - Intuitively, sorting is not an optimization problem, but still a simple illustration of applying the greedy method
  - Question to think about: can you formulate sorting as optimization?

#### GREEDY SORT -- SELECTION SORT --

- If you implement the greedy policy of finding the minimum by always scanning the remaining input, the resulting algorithm is a well-known sorting algorithm, called *Selection Sort*.
- It takes  $O(n^2)$  time, so it is not the best sorting algorithm
- **Question**: Can you give a faster implementation of the greedy policy of finding (and deleting) the minimum of the remaining input?

### **GREEDY SORT** -- BETTER IMPLEMENTATION--

- Since in greedy sorting you need to repeatedly find and delete the min, it makes sense to build and use an appropriate data structure
- Which standard data structure do that? Think delete-min()!!
- Answer: min-heaps
  - Which leads to ... (see next slide)

#### GREEDY SORT -- HEAPSORT --

**Template** Greedy (input I)

#### begin

**Optional: Process input I for faster exec** 

while (solution is not complete) do

Select the best element x in the

remaining input I;

Remove x from the input I;

Put x next in the output;

endwhile

end

• That is **Heapsort** 

• It takes  $O(n \log n)$  time. Pretty good!

# **LESSONS LEARNED SO FAR**

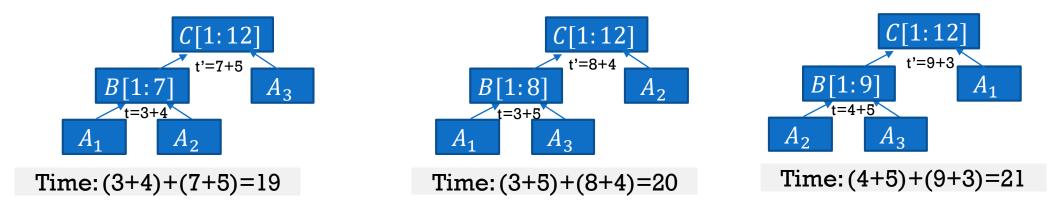
- The same greedy policy on the same problem can be implemented in different ways
- Some implementations can be much faster (e.g., min-heap leads to faster greedy sorting)
- Pre-processing the input can be very helpful
  - for faster implementation, and
  - sometimes for making greedy possible (to be seen later)
- More lessons to come (about the greedy method)

#### SECOND APPLICATION -- OPTIMAL MERGE PATTERNS --

- **Input**: n <u>sorted</u> arrays  $A_1[1:L_1], A_2[1:L_2], ..., A_n[1:L_n]$
- **Output**: The whole input combined into a <u>single</u> <u>sorted</u> array
- **Task**: Find a <u>greedy</u> algorithm that merges  $A_1, \ldots, A_n$  <u>pairwise</u> into a single sorted array, taking a <u>minimum # of steps</u>

#### **OPTIMAL MERGE PATTERNS** -- **AN EXAMPLE**--

- Example: Take three sorted arrays  $A_1[1:3], A_2[1:4], A_3[1:5]$
- Three ways (i.e., pairing sequences) to merge:



- Although all the different pairings lead to the same final output C[1:12], they take different amounts of time
- Interested in an algorithm that finds the fastest way

# **OPTIMAL MERGE PATTERNS** -- **A GREEDY ALGORITHM** --

- **Greedy policy**: at every step, must choose the "best" pair (of arrays) to merge
- **Best**: pair of the two shortest arrays
- Greedy policy: Select the two shortest arrays to merge next
- **Optimality question**: Is this greedy method guaranteed to give us an optimal solution, i.e., the sequence of pairings that take the least amount of time?
- **Answer**: Yes, the greedy solution for this problem is always optimal
- **Proof**: It will not be provided, but you can work on it as an exercise

#### **OPTIMAL MERGE PATTERNS** -- A GREEDY ALGORITHM: IMPLEMENTATION --

- The greedy algorithm is a loop where in every iteration:
  - we need to **<u>find</u>** the two **<u>smallest-length</u>** arrays,
  - remove them from the input, and
  - replace them, i.e., <u>insert</u> back to the input, with a <u>new</u> array of <u>new</u> length (sum of the previous two lengths)
- These operations are repeated over and over, so?
- So, better design/use a data structure of array lengths so we can find & delete the smallest-length very fast, and insert very fast

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- What data structure best meet those needs?
  - a. Stack?
  - b. Queue?
  - c. Binary search tree?
  - d. Min-heap?
- Time complexity of the greedy optimal merge pattern?
  - a.  $O(n^2)$
  - b.  $O(n \log n)$
  - **c.** *O*(*n*)

### THIRD APPLICATION -- THE KNAPSACK PROBLEM --

#### • Input:

- Items: 1, 2, 3, ..., n
- Weights:  $W_1 \quad W_2 \quad W_3 \quad \dots$ ,
- Prices:  $P_1$   $P_2$   $P_3$  ...,

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- Capacity:
- **Output**: How much of item *i* to take such that the total of the taken weights is  $\leq C$ , and the total of the prices of the taken items is maximized.

More formally:

- $\forall i$ , let  $x_i$  be the fraction (between 0 and 1) of item *i* to take. Ex: if  $x_i = \frac{1}{3}$ , that means we're taking  $\frac{1}{3}$  of item *i*, and so we're taking weight  $\frac{W_i}{3}$  (=  $x_i W_i$ ) and price  $\frac{P_i}{3}$  (=  $x_i P_i$ )
- Output: Find  $x_1, x_2, ..., x_n$  to maximize  $\sum_{i=1}^n x_i P_i$  such that  $\sum_{i=1}^n x_i W_i \leq C$
- **Task**: Write a greedy algorithm for solving this problem

 $P_i$  is the price of the

whole item i, not the

price per pound

 $W_n$ 

 $P_n$ 

#### THE KNAPSACK PROBLEM -- A GREEDY ALGORITHM: FIRST ATTEMPT --

- Solution is a sequence  $x_1, x_2, ..., x_n$
- At step *i*, compute the value  $x_i$
- **Greedy policy 1**: Select the item with the <u>smallest</u> weight from among the remaining items. If it still fits on the "sack" (of capacity C), take all of that item; otherwise, just take the largest fraction of it that fills the sack.
- **Rationale**: Since we're limited by total weight (C) that we can carry, if we always choose smallest-weight items, we end up with a lot of items, hoping that would maximize our profit.
- **Exercise**: Show that this greedy policy doesn't guarantee an optimal solution

#### HOW TO PROVE A GREEDY SOLUTION NOT OPTIMAL

- Method for proving non-optimality (by a counter-example)
  - 1. Construct an actual input (of size as small as possible)
  - 2. Find the greedy solution from that input
  - 3. Manually, find a better solution
- If you succeed in finding a better solution than the greedy solution, then obviously the greedy solution is non-optimal
- Note: the manual solution you find need not be optimal, i.e., <u>best;</u> it only needs to be <u>better</u> than the greedy solution.

# **LESSONS LEARNED SO FAR**

- The same greedy policy on the same problem can be implemented in different ways
- Some implementations can be much faster (e.g., min-heap leads to faster greedy sorting)
- Pre-processing the input can be very helpful
- The greedy method does not always guarantee optimality (as in some greedy policies for the knapsack problem)
- To prove non-optimality, use counter-examples
- More lessons to come (about the greedy method)

#### THE KNAPSACK PROBLEM -- A GREEDY ALGORITHM: SECOND ATTEMPT --

• **Greedy policy 2**: Select the item with the <u>largest</u> price.

Again, if it still fits in the sack (of capacity C), take all of that item; otherwise, just take the largest fraction of it that fills the sack.

- **Rationale**: by taking as many most expensive items as fit on the sack, we hopefully end up with maximum profit
- **Exercise**: Show that this greedy policy doesn't guarantee an optimal solution

#### THE KNAPSACK PROBLEM -- A GREEDY ALGORITHM: THIRD ATTEMPT --

• Greedy policy 3: Select the item with the highest price per unit weight,

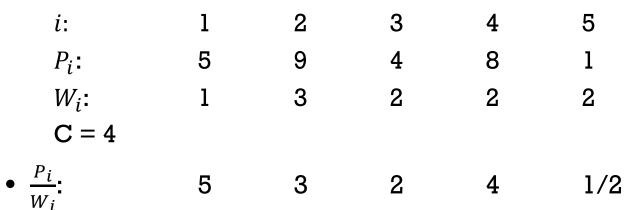
i.e., with the highest  $\frac{P_i}{W_i}$ , out of the remaining items.

Again, if it still fits on the sack (of capacity C), take all of that item; otherwise, just take the largest fraction of it that fills the sack .

- **Claim**: This policy guarantees that the greedy solution of the knapsack problem is always optimal
- **Proof**: It will not be given in this course.

#### THE KNAPSACK PROBLEM -- A GREEDY ALGORITHM: AN EXAMPLE --

• Example:



- Solution:
  - $1^{st}$  item to select: item 1, so  $x_1 = 1$ ,  $x_1W_1 = 1$  Weight so far=1
  - $2^{nd}$  item to select: item 4, so  $x_4 = 1, x_4 W_4 = 2$
  - 3<sup>rd</sup> item to select: item 2, so  $x_2 = \frac{1}{3}$ ,  $x_2 W_2 = \frac{3}{3} = 1$  Weight so far=4=C
  - Profit (i.e., total price taken):  $x_1P_1 + x_4P_4 + x_2P_2 = 1 \times 5 + 1 \times 8 + \frac{1}{3} \times 9 = 16$
  - Note that  $x_3 = 0$  and  $x_5 = 0$ .

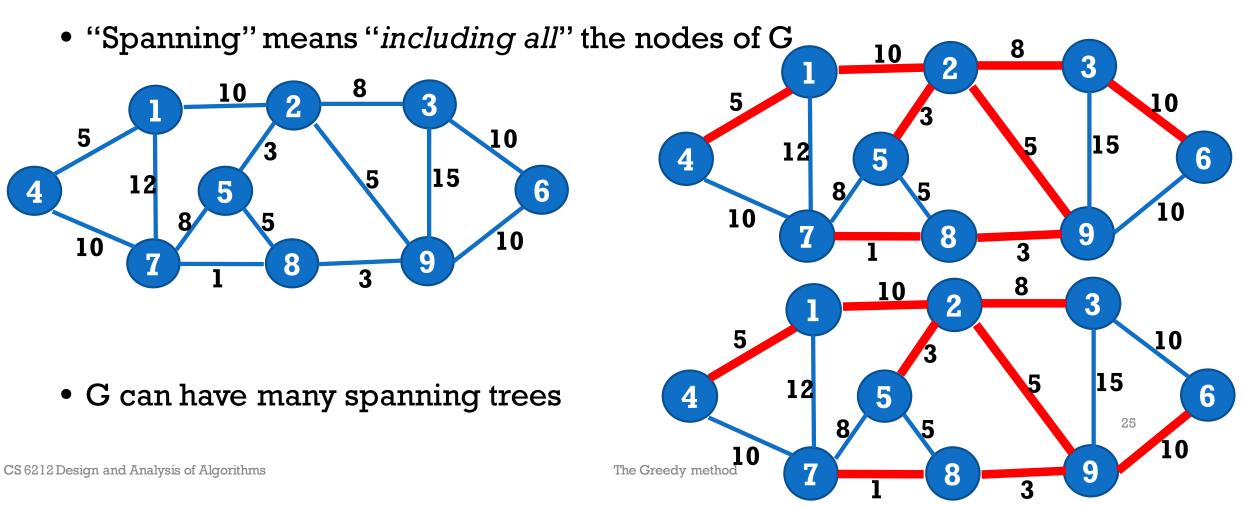
Weight so far=3

# **LESSONS LEARNED SO FAR**

- The same greedy policy on the same problem can be implemented in different ways
- Some implementations can be much faster
- Pre-processing the input can be very helpful
- The greedy method does not always guarantee optimality
- To prove non-optimality, use counter-examples
- For the same problem, one can formulate different greedy policies, some non-optimal and some optimal
- More lessons to come (about the greedy method)

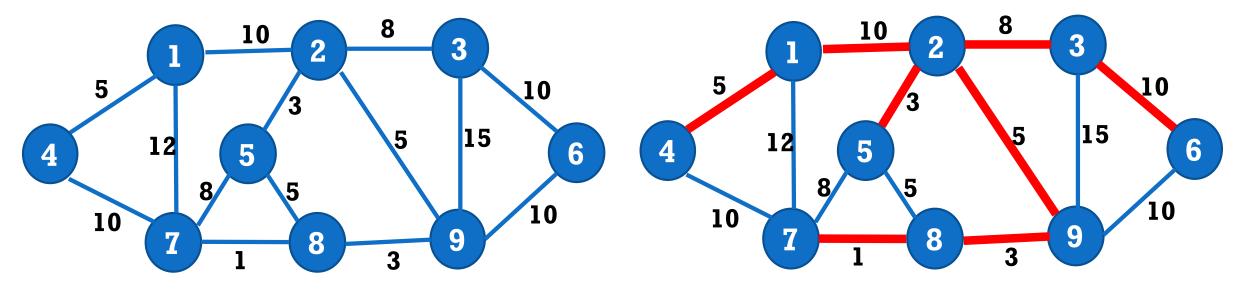
#### THE MINIMUM SPANNING TREE PROBLEM -- PRELIMINARY DEFINITIONS (1/2) --

• **Definition**: A *spanning tree* T of a graph G is a tree that has all the nodes of G such that every edge in T is an edge in G



#### THE MINIMUM SPANNING TREE PROBLEM -- PRELIMINARY DEFINITIONS (2/2) --

- **Definition**: If G is weighted, i.e., the edges have weights, then the **weight of T** is the **sum of the weights of its edges**
- **Definition:** A *minimum spanning tree* (MST) of a weighted graph G is a spanning tree that has minimum weight among all spanning trees of G.



#### THE MINIMUM SPANNING TREE PROBLEM -- STATEMENT OF THE PROBLEM--

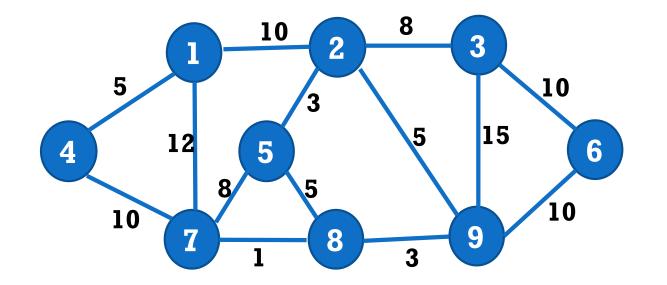
- **Input**: A weighted graph G, typically represented by a weight matrix W[1:n,1:n], where for non-edges (i,j):  $W[i,j] = \infty$
- **Output**: A minimum spanning tree in G
- **Task:** Develop a greedy algorithm that finds a MST in any input weighted graph

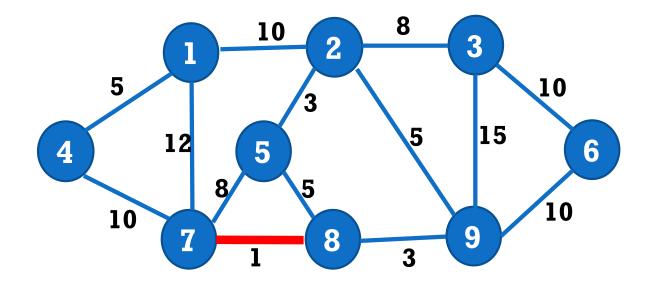
#### **GREEDY ALGORITHM FOR THE MST PROBLEM** -- **KRUSKAL'S ALGORITHM** --

- Solution as a set of elements: the elements are the edges of the tree
- The Greedy method will find the tree one edge at a time
- Greedy policy: At every step, select (and remove) the minweight edge out of the remaining edges in the graph
- Can we always add a selected edge to the growing tree T?
  - No, not always: if the selected edge would create a cycle in T, it must not be added (recall that a tree has no cycles)
- Adjustment to the greedy method: if the min-weight edge creates a cycle in T, throw it out; else, add it to T

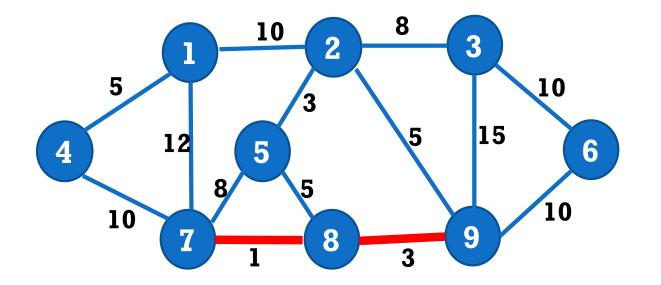
### PSEUDOCODE OF KRUSKAL'S GREEDY MST ALGORITHM

**Procedure** ComputeMST(**in**: W[1:n,1:n]; **out**: T) // non-edges (*i*, *j*):  $W[i,j] = \infty$ begin Put in T all the n nodes and no edges; while T has less than n-1 edges do Select a min-weight edge e out of the remaining edges; Delete e from the graph; if (e does not create a cycle in T) then Add e to T; endif endwhile end ComputeMST

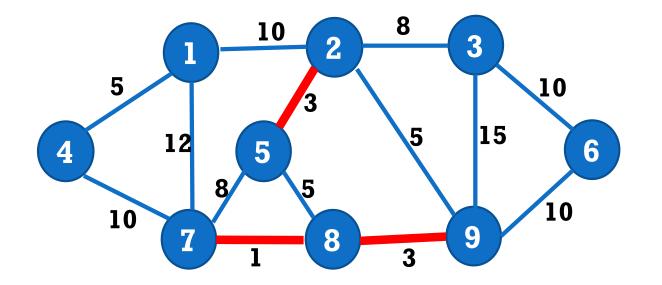




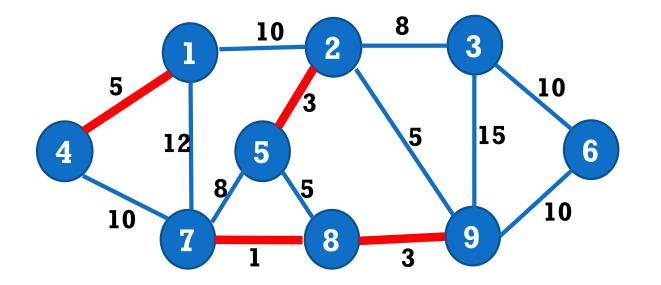
• Min edge: (7,8). No cycle => OK to add



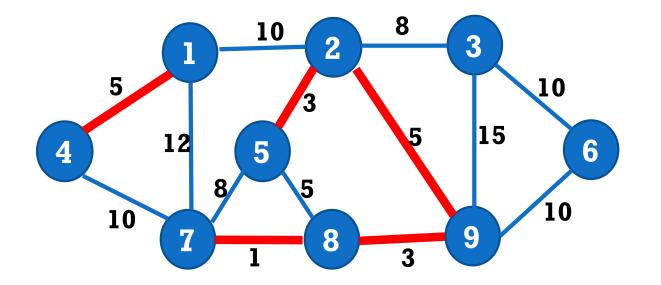
• Min edge: (8,9), (2,5). Pick (8,9). No cycle => OK to add



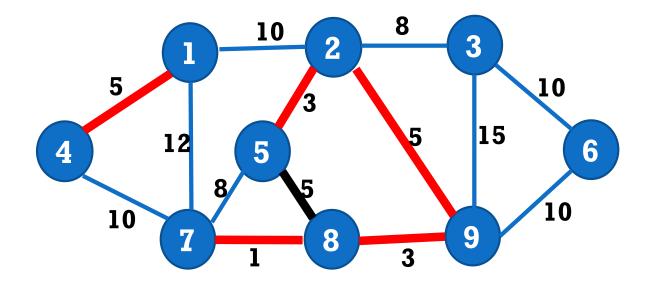
• Min edge: (2,5). No cycle => OK to add



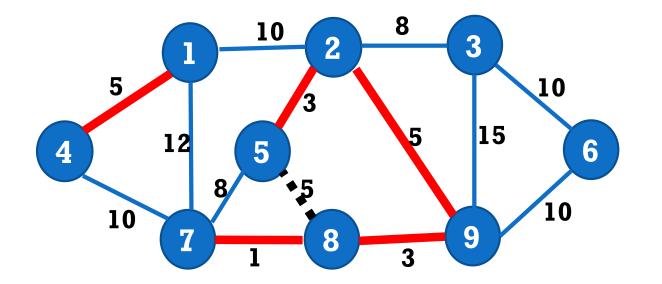
• Min edge: (1,4), (2,5), (5,8). Pick (1,4): No cycle => OK to add



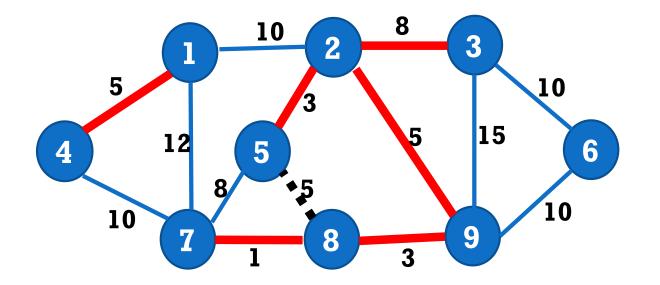
• Min edge: (2,5), (5,8). Pick (2,5). No cycle => OK to add



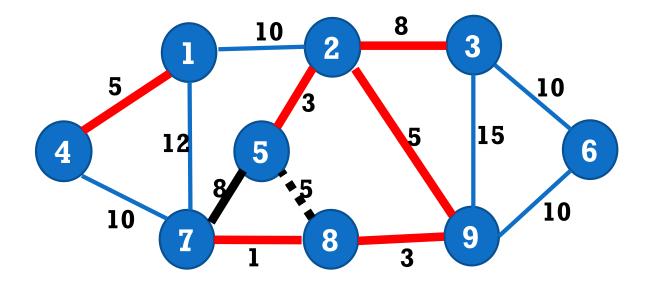
#### • Min edge: (5,8). Creates cycle



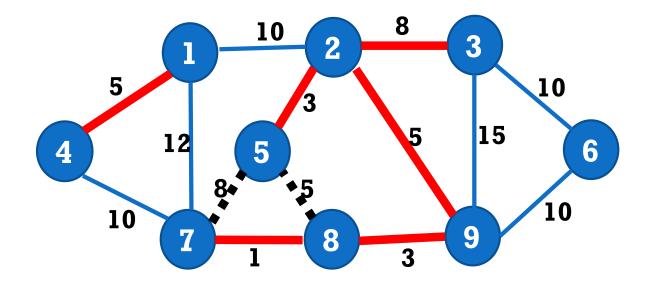
• Min edge: (5,8). Creates cycle => throw it out



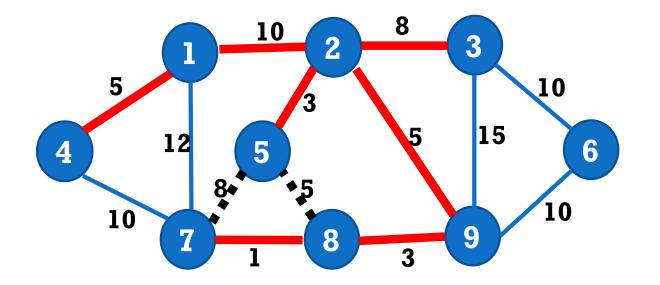
• Min edge: (2,3) and (5,7). Pick (2,3): No cycle => OK to add



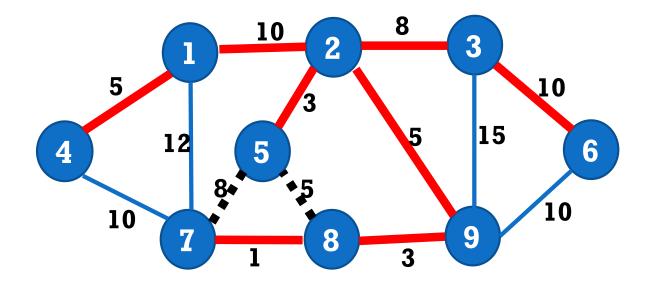
### • Min edge: (5,7). Creates cycle



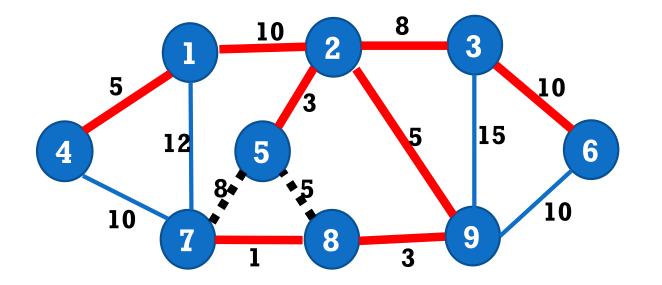
• Min edge: (5,7). Creates cycle => throw it out



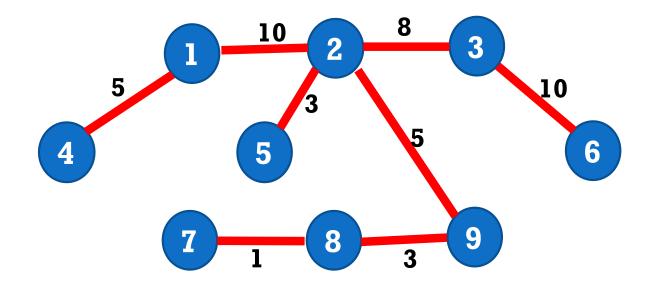
• Min edge: (1,2), (3,10), (4,7), 6,9). Pick (1,2): No cycle => OK to add



• Min edge: (3,6), (4,7), (6,9). Pick (3,6): No cycle => OK to add



#### • Tree completed (got 8 edges)

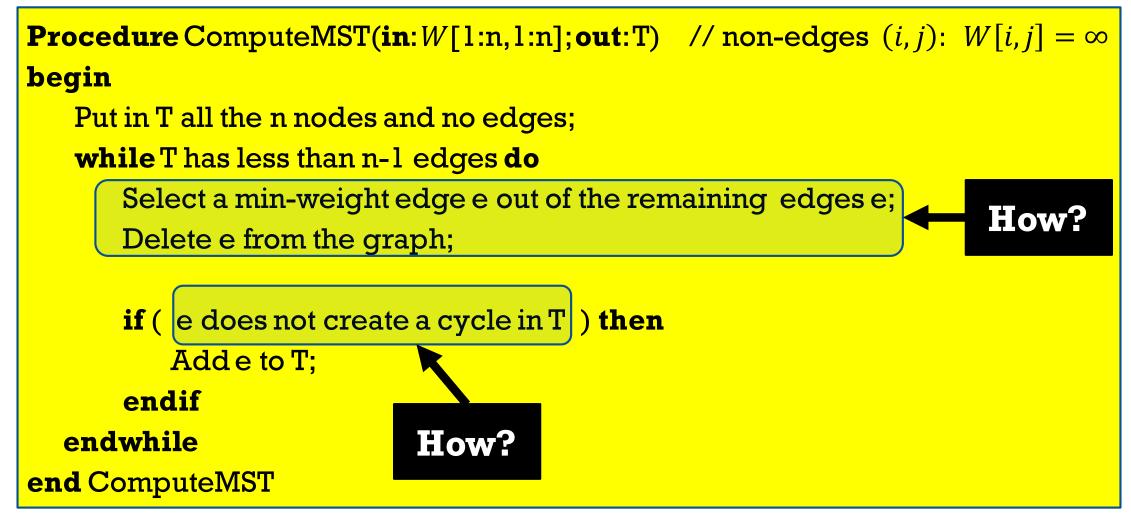


### • This is the spanning tree produced by the greedy algorithm

## THE GREEDY MST ALGORITHM -- IMPLEMENTATION ISSUES --

**Procedure** ComputeMST(**in**: W[1:n,1:n]; **out**: T) // non-edges (i, j):  $W[i, j] = \infty$ begin Put in T all the n nodes and no edges; while T has less than n-1 edges do Select a min-weight edge e out of the remaining edges e; Delete e from the graph; if ( e does not create a cycle in T ) then Adde to T; endif endwhile end ComputeMST

## THE GREEDY MST ALGORITHM -- IMPLEMENTATION ISSUES --



## THE GREEDY MST ALGORITHM -- IMPLEMENTATION: FINDING-DELETING MIN-EDGE --

- Since we want to repeatedly find the min-weight edge and delete it from the set of edges, it is good to build a data structure to do that
  - What suitable data structure?
    - Min-heap (of edges, where the key=weight)
    - Build a heap at the start of the MST algorithm
- Alternative solution?
  - Sort the edges (by weight) from at the start of MST algorithm
  - Consider the edges in that sorted order

## THE GREEDY MST ALGORITHM

-- IMPLEMENTATION: CHECKING IF EDGE CREATES CYCLE --

Ex: e=(2,9)

15

9

3

9

15

6

6

8

8

10

5

5

10

10

2

8

8

- During the algorithm, T is a "forest" of small trees
- When an edge e=(x,y) is being tested if it creates a cycle in T:
  - Node x belongs to one small tree, and so does y
  - If x and y belong to <u>different</u> small trees (regardless of the shape of the trees ):
    - Adding edge (x,y) will not create a cycle
    - So add it.
  - If x and y belong to the **same small tree** :
    - Adding edge (x,y) creates a cycle
- So, if we can <u>find</u> which small tree has x, and which has y, we can check for cycles
- Of course, when we add an edge, the two small trees combine into a new small tree (and the two old small trees no longer exit separately) 48

**Ex: e=(5,8)** 

## **THE GREEDY MST ALGORITHM**

#### -- CHECKING IF EDGE CREATES CYCLE: HOW?--

- Do we know of a data structure
  - that can find which tree (or set of elements) contains a given element/node x (or y), and
  - that can combine two old sets to a new set after which the two old sets no longer exit separately?
- The Union-Find data structure does exactly those two operations!!

### THE GREEDY MST ALGORITHM -- IMPLEMENTATION --

```
Procedure ComputeMST(in: W[1:n,1:n]; out: T) // non-edges (i, j): W[i,j] = \infty
begin
   integer PARENT[1:n]=[-1,-1,...,-1;
                                     // for Union-Find
   Build a minheap H[1:|E|] for all the |E| edge
   Put in T the n nodes and no edges;
   while (T has less than n-l edges) do
      e=delete-min(H); // assume e=(x,y)
      r1 := F(x); r2 := F(y);
      if (r1 != r2) then
          Adde to T;
          U(r1,r2);
      endif
 endwhile
end ComputeMST
```

## THE GREEDY MST ALGORITHM -- TIME COMPLEXITY ANALYSIS--

<b>Procedure</b> ComputeMS	T( <b>in</b> :W[l:n,l:n]; <b>out</b> :T)	// non-edges $(i, j)$ : $W[i, j] = \infty$					
begin							
integer PARENT[1:n]	// for Union-Find						
Build a minheap H[1:	E ]for all the  E  edge						
Put in T the n nodes a	and no edges;	Iterates  E  times, not n-1 times.					
while (T has less that	Why?						
e=delete-min(H); // assume e=(x,y)							
rl := F(x); r2 := F	'(y);						
<b>if</b> (rl != r2) <b>then</b>							
Adde to T;	<ul> <li>O( E ) to build the l</li> </ul>	heap					
U(r1,r2);	<ul> <li>Up to  E  calls to de</li> </ul>	elete-min: $O( E \log E )$ time					
endif	<ul> <li>Up to  E  calls to U a</li> </ul>	and F: $O( E \log n)$ time					
endwhile	• Therefore, the total t	ime: $O( E  \log  E )$					
end ComputeMST							

## **PROOF OF OPTIMALITY OF THE GREEDY MST**

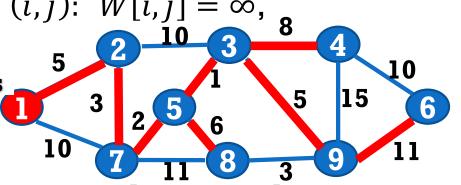
- Next lecture:
  - We will prove that the spanning tree T produced by the greedy algorithm is indeed a minimum spanning tree

## **LESSONS LEARNED SO FAR**

- The same greedy policy on the same problem can be implemented in different ways
- Some implementations can be much faster (e.g., min-heap 4 greedy sorting)
- Pre-processing the input can be very helpful (e.g., sorting P/W)
- The greedy method does not always guarantee optimality
- To prove non-optimality, use counter-examples
- For the same problem, one can formulate different greedy policies, some nonoptimal and some optimal
- Some greedy selections may have to be discarded sometimes (like in MST)
- More lessons to come (about the greedy method)

### THE SINGLE-SOURCE SHORTEST PATHS PROBLEM -- PROBLEM STATEMENT --

- Input:
  - A weighted connected graph G=(V,E), represented by its weight matrix W[1:n,1:n], where for non-edges (i,j):  $W[i,j] = \infty$ , and  $\forall i, W[i,i] = 0$
  - A source node **s** of **G**.
- **Output**: Shortest paths from source



nodes to every other node in the graph, one path per node

- **Simpler output:** distance[1:n] where distance[*i*] is the distance from source node s to node *i*, i.e., the length of the shortest path from s to *i*.
- **Task:** Develop a greedy algorithm for this problem

## SINGLE-SOURCE SHORTEST PATHS (SSSP) -- GREEDY METHOD PRELIMINARIES--

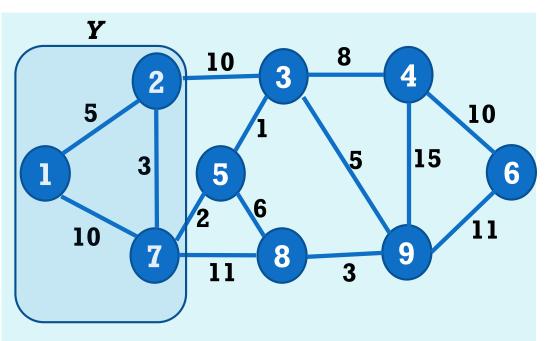
- **Issue**: It is not clear how the solution can be viewed as a set/sequence of elements? What are the elements?
- Recall that sometimes we need to pre-process the input: to make the solution more efficient, and/or to make the greedy solution *formulatable*
- New concepts and definitions will be introduced so a greedy method can be formulated



### -- DISTANCE APPROXIMATIONS: SPECIAL PATHS --

- Let **Y** be a set := {s} initially
- **Definition**: A path from s to a node x outside Y is called *special path* if each intermediary node on the path belongs to Y.
- Let DIST[1:n] be:
  - DIST[i] = the length of the shortest special path from s to i
- **Greedy selection policy**: choose from outside *Y* the node of minimum DIST value, and add it to *Y*
- **Claim** (proved later) :

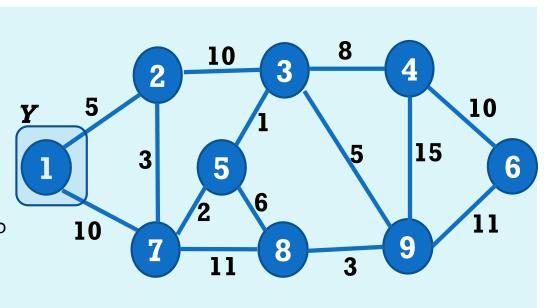
 $\forall i \in Y, DIST[i] = distance[i]$ , that is, when a node *i* joins *Y*, its DIST is equal to its distance from s.



- Special paths:
  - 1,2,3 because 1 is source, and 1 and 2 are inside Y
  - 1,2,7,5 b/c 1 is source and 1,2, and 7 are inside Y
  - 1,5 (missing edge is an edge of weight  $\infty$ )
- Not Special paths: 1, 2, 3, 4 (b/c 3 is not in Y); 1, 7, 5, 8 (Why?)



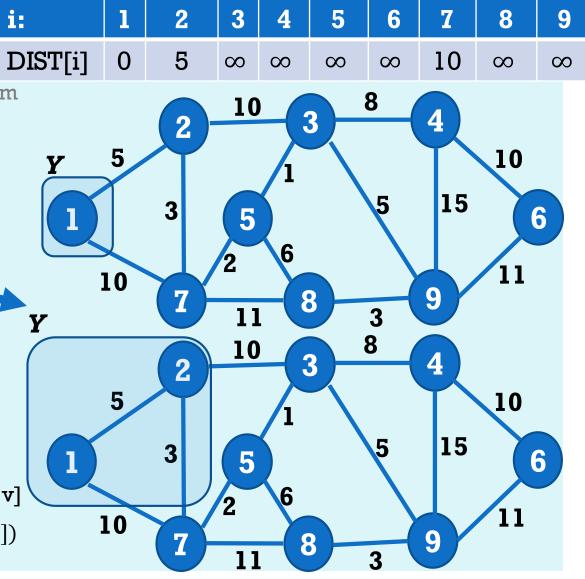
- Initially:
  - Y={s}
  - ∀i ∈ V, the only special path from s to
     i is the edge (s.i), either a real edge of
     a finite weight, or imaginary of weight ∞
  - Therefore, DIST[i]=W[s,i]
  - In this example:



<b>i</b> :	1	2	3	4	5	6	7	8	9
DIST[i]	0	5	$\infty$	$\infty$	$\infty$	$\infty$	10	$\infty$	$\infty$

## **SPECIAL PATHS: UPDATES**

- Greedy selection:
  - Choose from outside *Y* the node of minimum DIST value, and add it to *Y*. Call it u
- In this example, u=2 (DIST[2]=5)
- Add 2 to Y: Y={1,2}
- How does DIST change?
  - For any node v outside Y, v gained new special paths, the shortest of which is:
     MinSpecialPath[s → u]+(u,v) of length:
     DIST[u] + W[u,v])
  - This new special path may be shorter or longer than the precious MinSpecialPath[s → v]
  - $\therefore DIST[v] = \min(DIST[v], DIST[u] + W[u, v])$



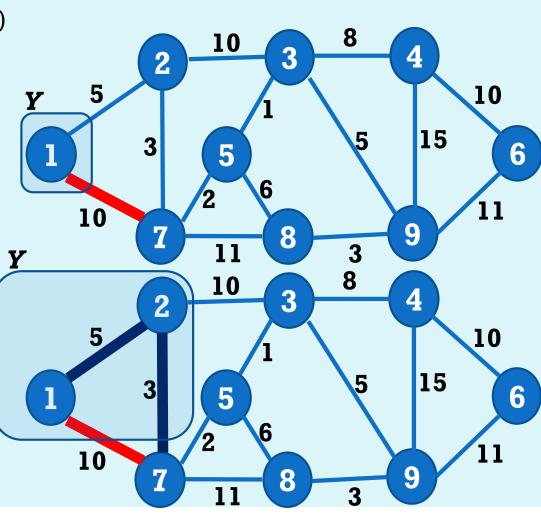
### SPECIAL PATHS -- UPDATES EXAMPLE --

• DIST[v] = min(DIST[v], DIST[u] + W[u,v])

<b>i</b> :	1	2	3	4	5	6	Z	8	9
DIST[i]	0	5	$\infty$	$\infty$	$\infty$	$\infty$	10	$\infty$	$\infty$

- Before update: DIST[7]=10
- After update: DIST[7]= min(10, DIST[2]+W[2,7])= min(10, 5+3)=8.
- DIST[3]=min(∞, DIST[2]+W[2,3])=15

i:	1	2	3	4	5	6	Z	8	9
DIST[i]	0	5	15	$\infty$	$\infty$	$\infty$	8	$\infty$	$\infty$

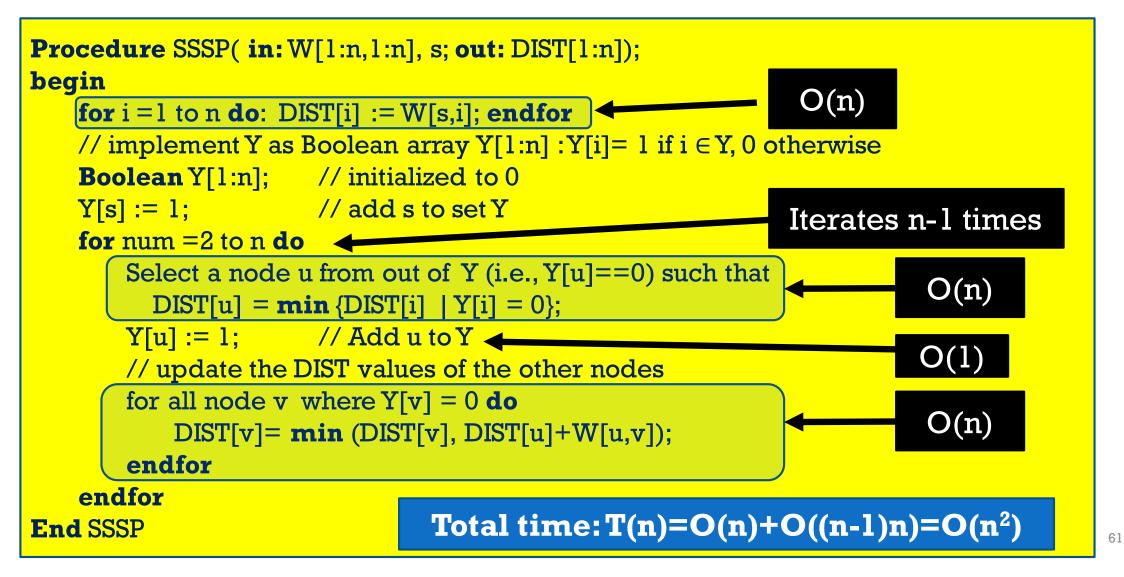


The Greedy method

## **GREEDY SSSP ALGORITHM**

```
Procedure SSSP( in: W[1:n,1:n], s; out: DIST[1:n]);
begin
   for i = 1 to n do: DIST[i] := W[s,i]; endfor
   // implement Y as Boolean array Y[1:n]:Y[i] = 1 if i \in Y, 0 otherwise
   Boolean Y[1:n]; // initialized to 0
   Y[s] := 1; // add s to set Y
   for num =2 to n do
       Select a node u from out of Y (i.e., Y[u] = = 0) such that
         DIST[u] = min \{DIST[i] | Y[i] = 0\};
       Y[u] := 1; // Add u to Y
       // update the DIST values of the other nodes
       for all node v where Y[v] = 0 do
           DIST[v] = min (DIST[v], DIST[u]+W[u,v]);
       endfor
   endfor
End SSSP
```

## **GREEDY SSSP ALGORITHM COMPLEXITY**

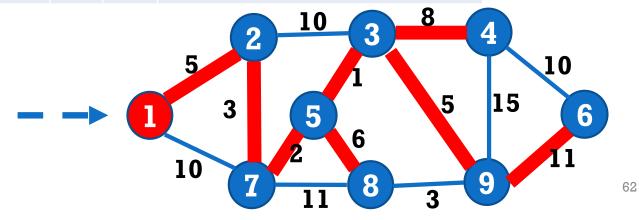


# GREEDY SSSP

#### -- COMPLETE EXAMPLE --

i	1	2	3	4	5	6	Z	8	9	Y={1}
DIST[i]	0	5	$\infty$	$\infty$	$\infty$	$\infty$	10	$\infty$	$\infty$	$u=2 \rightarrow Y=\{1,2\}$
DIST[i]	0	5	15	$\infty$	$\infty$	$\infty$	8	$\infty$	$\infty$	$u=7 -> Y=\{1,2,7\}$
DIST[i]	0	5	15	$\infty$	10	$\infty$	8	19	$\infty$	$u=5 \rightarrow Y=\{1,2,7,5\}$
DIST[i]	0	5	11	$\infty$	10	$\infty$	8	16	$\infty$	$u=3 \rightarrow Y=\{1,2,7,5,3\}$
DIST[i]	0	5	11	19	10	$\infty$	8	16	16	$u=8 \rightarrow Y=\{1,2,7,5,3,8\}$
DIST[i]	0	5	11	19	10	$\infty$	8	16	16	u=9->Y={1,2,7,5,3,8,9}
DIST[i]	0	5	11	19	10	27	8	16	16	u=4 -> Y=1,2,7,5,3,8,9,4}
DIST[i]	0	5	11	19	10	27	8	16	16	U=6->Y=1,2,7,5,3,8,9,4,6}

Shortest paths from 1 to the other nodes, highlighted in red edges



The Greedy method

## **LESSONS LEARNED SO FAR**

- The same greedy policy on the same problem can be implemented in different ways
- Some implementations can be much faster (e.g., min-heap for greedy sorting)
- Pre-processing the input can be very helpful (e.g., sorting P/W)
- The greedy method does not always guarantee optimality
- To prove non-optimality, use counter-examples
- For the same problem, one can formulate different greedy policies, some non-optimal and some optimal
- Sometimes greedy selections may have to be discarded sometimes (like in MST)
- Sometimes, problems may have to be reformulated to make the greedy formulatable (as in SSSP)
- More lessons to come (about the greedy method)

## **OPTIMALITY OF THE GREEDY SSSP**

- Next lecture
  - We will show that the final DIST values of all the nodes are indeed the distances (i.e., lengths of shortest paths) from s to the other nodes

## **ADDITIONAL WORK (1)**

#### • An exercise for the students:

How will you modify the greedy SSSP algorithm so it returns the actual shortest paths, not just the distances

### • Helpful observations:

- The greedy-selected shortest paths from s to all the nodes form a tree rooted at s
- Have the edges of that tree point backward (towards the root s)
- Your modified greedy SSSP can include that tree, and updates to Y and DIST can translate to updates to that tree
- Once the tree is fully derived, the shortest paths can be generated by tracing back from each node to the root s (and then reversing those paths)

## ADDITIONAL WORK (2) -- THE COIN CHANGE PROBLEM --

#### • Input:

- A currency system made up of an unlimited number of coins of the following denominations, i.e., values, {C<sub>1</sub>, C<sub>2</sub>, ..., C<sub>m</sub>}. For example, denominations {1, 5, 10, 25} representing a penny, nickel, dime, and quarter.
- An amount N (like N cents)
- **Output**: A minimum number of coins whose total value is N
- **Task**: Formulate a greedy algorithm for this problem

#### • Questions:

- Does your greedy algorithm guarantee optimality (i.e., guarantee that the number of coins making up the change N is minimum)? For an any arbitrary currency system? For the American coinage system ({1,5,10,25})?
- If for some currency systems the greedy method doesn't guarantee optimality, give a counter-example of a currency system and an N for which the greedy solution is not best